L0099901 Emergency Kit Samsung Nextmove Drive Repair

Operating procedures and instructions for the emergency repair kit for Samsung / Nextmove machines

Contents	
Goal	
Warranty	
Machines Covered	
Process	
Parts	
Drive Parameter Settings	
Drawings	
Encoder Cables to Nextmove	
Motor Cable Plugs	
Comments	

Goal

This kit is to simplify the process of identifying and repairing drive and motor problems on site on older obsolete systems. It uses the spare service exchange stock harvested from refurbishments, rebuild and drive upgrades. This kit solves the following problems

- Attempting to successfully diagnose a faulty problem on phone support
- Successfully identifying the correct stock items
- Sending an engineer without the correct parts
- Reducing cost to customer where the root cause of a problem is not clear
- Improve first time fix, as all potential parts are on site to test
- Move the drive programming function to the engineer on site by sending a drive programming unit

▲ ...The drive programmers are extremely rare so must be treated with care and must be returned

Warranty

These parts are offered as second and emergency repair item only and are not offered with a warranty

Machines Covered

This kit is only suitable for the following machine types, using a Nextmove control system. Does not apply to machines that have been upgraded to the Beckhoff control system

Process

Team	Trigger	Task
Service Support	Customer reports a drive / servo problem	Attempt phone and online diagnostics. If parts are needed request L0099901 Liaise with parts team to book engineer to meet crate on site (PO from customer needed)
Parts	Customer / service request for quote	Quote for L0099901
Parts	Wait for customer PO	Process Sales Order Arrange pick up / returns form - add to crate
Stores	Sales order requested	Dispatch crate for next day delivery
Stores	Crate received back to Stuga	Replenish missing stock items Update the free text works order with parts identified

Parts

R0099	9901	Box Contents of L0099901 Emergency Kit for Samsung Next									
ő	1	C0000151X !! Samsung Servo Motor (X ,Y, Z, Saw) SX Service Exch CSMT_08BB1ANT3									
S.	1	C0000153SX !! Servo Motor: Samsung CSMH (R Axis)	ZF02A3								
	2	C00001555X !! Servo Drive: Samsung Fara 1kW Service Exchange	ZF01C1								
	1	C0000157SX Servo Drive: Samsung Fara Breakout Panel Service Exch	ZF00C1								
9	1	C0000190-SX 11 Amp Drive for V Y & Z Axis DM 110	ZF00D2								
	1	C0000280SX Stepper Enclosure: SA46/XO40 3 Axis + PSU (ZX)	ZF00A2								
\$	1	C0000342-SX !! Nextmove E100 NXE100-1608SB (Service Exc.)	ZF00D4								
	1	C0000384-SX !! Nextmove ESB-2 with Open Collector Outputs NSB20	ZF00D4								
205	5	E0000259 Connector: 4Way, Female Housing, 4.2mm Pitch (Mate- 483–8663 Samsung Servo Ca	ZA05A3 able Power Plug								
100	5	E0000261 Connector: 9Way, Female Housing, 4.2mm Pitch (Mate- 483–8685 Samsung Feedback Cab	ZA05A4 Ile Plug Housing								
Simon Bar	25	E0000262 Connector: Female Pin for E0000261, 22AWG (Mate-N- 274-2251 Samsung Feed	ZA05A4 back Cable Pins								
Lange	25	E0000284 Connector: Male Pin for E0000285, 22AWG (Mate-N-Lo 274–2223	ZA05A4								
R.	5	E0000285 Connector: 9Way, Male Housing, 4.2mm Pitch (Mate-N- 483-8607	ZA05A3								

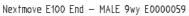
Drive Parameter Settings

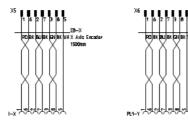
		Router	Eco		Standalone	Saw	Flowline / ZX / Microline								
		X Axis	X Axis (Sml mtr)		Saw		X Axis		Y Axis		Z Axis	R Axis	R Axis	Saw Pusher	
Parameter			Std Hand	Opp Hand	Std Hand	Opp Hand	SH	он		OH Zx		CSMH	RSMH	SH	он
1	Rpm per Volt	500	500	500	500	500	500	500	500		500	500	500	500	500
2	P Gain	60	277	277	125	125	65	65	110		250	40	40	65	65
3	l Gain	46	356	356	45	45	25	25	50		160	33	33	25	25
4	Pos P Gain	50	15	15	50	50	23	23	23		23	23	23	23	23
6	T Cut Off Freq	250	879	879	500	500	600	600	500		750	750	750	600	600
34	Pos FF Gain	50	50	50	50	50	0	0	0		0	0	0	0	0
36	Gear Num	2048	2048	2048	2048	2048	1024	1024	1024		1024	2048	2048	1024	1024
37	Gear Denom	400	8192	8192	400	400	2048	2048	2048		2048	1024	1024	2048	2048
40	Speed cutof freq	200	251	251	200	200	0	0	0		0	0	0	0	0
41	Control Mode	0	0	0	1	1	1	1	1		1	0	0	1	1

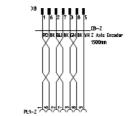
44		10	0	0	0	1000	0	1000	1000	0	1000	0	0	1000	0
44-1	Stop Method	0	0	0	0	0	0	0	0	0	0	0	0	0	0
44-2	After Stop	1	0	0	0	0	0	0	0	0	0	0	0	0	0
44-3	Emergency Stop	0	0	0	0	0	0	0	0	0	0	0	0	0	0
44-4	Encoder O/p dir	0	0	0	0	1	0	1	1	0	1	0	0	1	0
45		0	0	0	0	1000	0	1000	1000	0	1000	1000	1000	1000	0
45-1	Zero Clamp	0	0	0	0	0	0	0	0	0	0	0	0	0	0
45-2	Trapez / Scurve	0	0	0	0	0	0	0	0	0	0	0	0	0	0
45-3	Torque filter	0	0	0	0	0	0	0	0	0	0	0	0	0	0
45-4	Fwd / Reverse	0	0	0	0	1	0	1	1	0	1	1	1	1	0
45-5	Pulse O/p cct	0	0	0	0	0	0	0	0	0	0	0	0	0	0
46		40008	40008	40008	40000	40000	40008	40008	40008		40008	40008	40008	40008	40008
46-1	Pulse Form	8	8	8	0	0	8	8	8		8	8	8	8	8
46-2	Select Set 01 Unit	0	0	0	0	0	0	0	0		0	0	0	0	0
46-3	Reserved	0	0	0	0	0	0	0	0		0	0	0	0	0
46-4	Function of CN1 10pin	0	0	0	0	0	0	0	0		0	0	0	0	0
46-5	Function of CN1 15pin	4	4	4	4	4	4	4	4		4	4	4	4	4
51	Encoder Type	1	1	1	1	1	1	1	1		1	100	107	1	1
52	Motor Type	1012	1012	1012	1012	1012	1012	1012	1012		1012	2322	2422	1012	1012
53	Motor Capacity	80	100	100	80	80	80	80	80		80	100	100	80	80

Drawings

Encoder Cables to Nextmove







Drive end use FEMALE 9wy E0000046 For BALDOR drive add E0000/135 Gender Changer

Motor Cable Plugs

150

	nsung Moto	_	9	R9537, R3906, R390 R3908, R3909,	7,	Sam Soci Lead	ket	-	ı		
Power	WHT	PNK/ RED	(E288 4 E284 P	4 WAY PLUG INS)	Power			1	2		4 WAY SOCKET SOCKETS)
Viewed From Behind	GRN/ TUR	BLK			Viewed F Behind	From		3	GND		
Resolver					Resolver			-6	5		
	GRN	BLU/ BLK	BLU					RED	BLU	BRN	
Viewed From Behind	YEL/ BLK	ITEL	grn/ Blk	(E285 9 WAY PLUG E284 PINS)	Viewed F Behind	From		WHT	YEL	GRN	(E261 9 WAY SOCKET E262 SOCKETS)
	SCR	BLK R	RED			l		GRY	PNK	SCR	